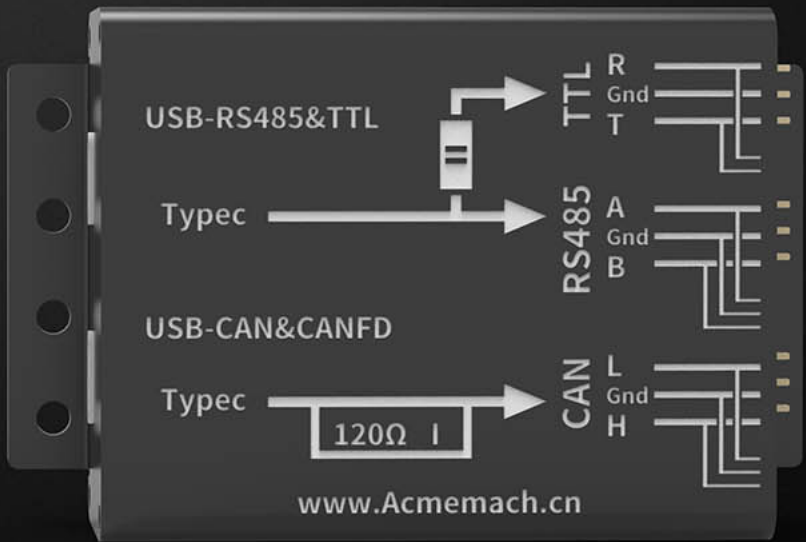
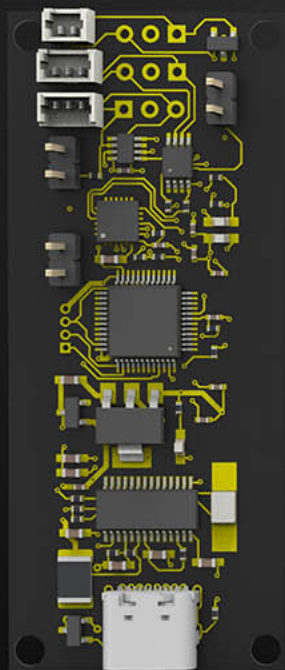
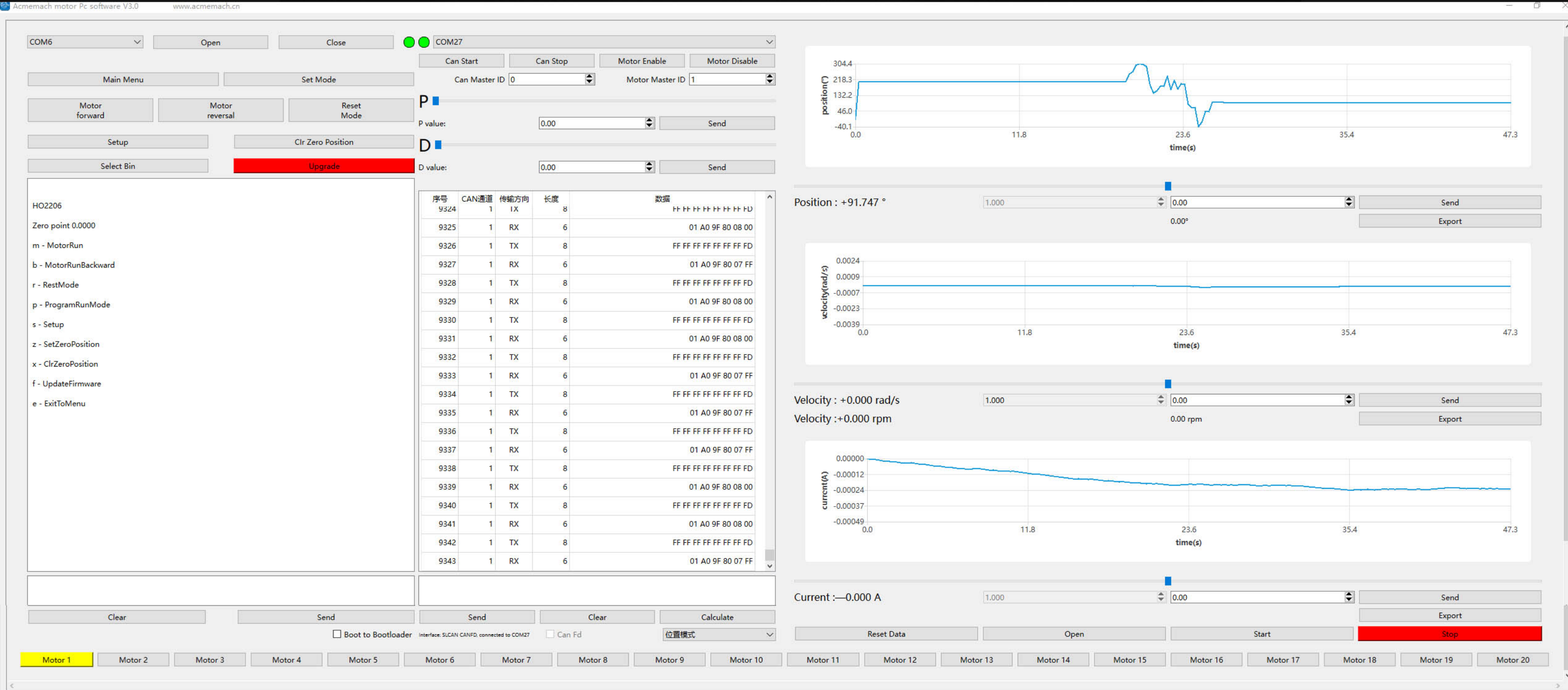


支持以下三款调试器



(停产)



COM6

HO2206

Zero point 0.0000

m - MotorRun

b - MotorRunBackward

r - RestMode

p - ProgramRunMode

s - Setup

z - SetZeroPosition

x - ClrZeroPosition

f - UpdateFirmware

e - ExitToMenu

电机配置界面

 ☐ Boot to Bootloader

COM27

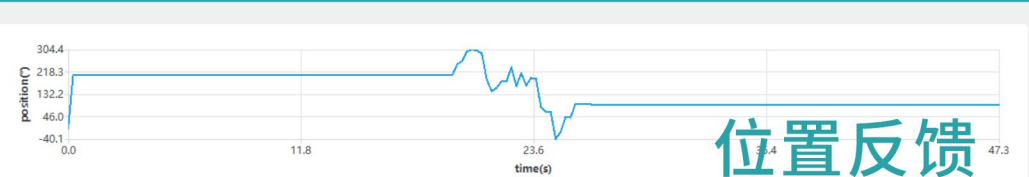
Can Master ID Motor Master ID

value:

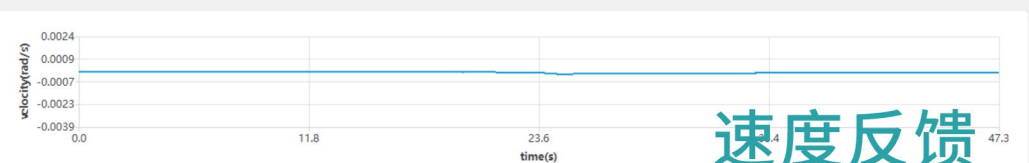
value:

序号	CAN通道	传输方向	长度	数据
9324	1	TX	8	FF FF FF FF FF FF FF FF
9325	1	RX	6	01 A0 9F 80 08 00
9326	1	TX	8	FF FF FF FF FF FF FF FF
9327	1	RX	6	01 A0 9F 80 07 FF
9328	1	TX	8	FF FF FF FF FF FF FF FF
9329	1	RX	6	01 A0 9F 80 08 00
9330	1	TX	8	FF FF FF FF FF FF FF FF
9331	1	RX	6	01 A0 9F 80 08 00
9332	1	TX	8	FF FF FF FF FF FF FF FF
9333	1	RX	6	01 A0 9F 80 07 FF
9334	1	TX	8	FF FF FF FF FF FF FF FF
9335	1	RX	6	01 A0 9F 80 07 FF
9336	1	TX	8	FF FF FF FF FF FF FF FF
9337	1	RX	6	01 A0 9F 80 07 FF
9338	1	TX	8	FF FF FF FF FF FF FF FF
9339	1	RX	6	01 A0 9F 80 08 00
9340	1	TX	8	FF FF FF FF FF FF FF FF
9341	1	RX	6	01 A0 9F 80 08 00
9342	1	TX	8	FF FF FF FF FF FF FF FF
9343	1	RX	6	01 A0 9F 80 07 FF

电机控制界面

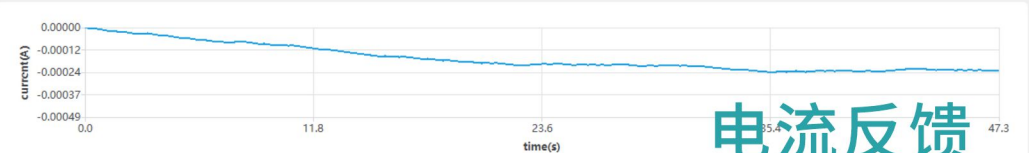
 Interface: SLCAN CANFD, connected to COM27 ☐ Can Fd 

Position : +91.747 °



Velocity : +0.000 rad/s

Velocity : +0.000 rpm



Current : -0.000 A

Motor 1

Motor 2

Motor 3

Motor 4

Motor 5

Motor 6

Motor 7

Motor 8

Motor 9

Motor 10

Motor 11

Motor 12

Motor 13

Motor 14

Motor 15

Motor 16

Motor 17

Motor 18

Motor 19

Motor 20

打开串口

关闭串口

打开CAN口

关闭CAN口

电机使能

电机失能

COM6

Open

Close

Main Menu

Set Mode

Motor forward

Motor reversal

Reset Mode

Setup

Clr Zero Position

Select Bin

Upgrade

HO2206

Zero point 0.0000

m - MotorRun

b - MotorRunBackward

r - RestMode

p - ProgramRunMode

s - Setup

z - SetZeroPosition

x - ClrZeroPosition

f - UpdateFirmware

e - ExitToMenu

Clear

Send

Motor 1

Motor 2

Motor 3

Motor 4

Motor 5

Motor 6

Motor 7

Motor 8

Motor 9

Motor 10

Motor 11

Motor 12

Motor 13

Motor 14

Motor 15

Motor 16

Motor 17

Motor 18

Motor 19

Motor 20

COM27

Can Start

Can Stop

Motor Enable

Motor Disable

Can Master ID 0

Motor Master ID 1

位置模式PD参数

D values: 0.00

Send

序号	CAN通道	传输方向	长度	数据
9324	1	TX	8	FF FF FF FF FF FF FF FD
9325	1	RX	6	01 A0 9F 80 08 00
9326	1	TX	8	FF FF FF FF FF FF FF FD
9327	1	RX	6	01 A0 9F 80 07 FF
9328	1	TX	8	FF FF FF FF FF FF FF FD
9329	1	RX	6	01 A0 9F 80 08 00
9330	1	TX	8	FF FF FF FF FF FF FF FD
9331	1	RX	6	01 A0 9F 80 08 00
9332	1	TX	8	FF FF FF FF FF FF FF FD
9333	1	RX	6	01 A0 9F 80 07 FF
9334	1	TX	8	FF FF FF FF FF FF FF FD
9335	1	RX	6	01 A0 9F 80 07 FF
9336	1	TX	8	FF FF FF FF FF FF FF FD
9337	1	RX	6	01 A0 9F 80 07 FF
9338	1	TX	8	FF FF FF FF FF FF FF FD
9339	1	RX	6	01 A0 9F 80 08 00
9340	1	TX	8	FF FF FF FF FF FF FF FD
9341	1	RX	6	01 A0 9F 80 08 00
9342	1	TX	8	FF FF FF FF FF FF FF FD
9343	1	RX	6	01 A0 9F 80 07 FF

Send

Clear

Calculate

Interface: SLCAN CANFD, connected to COM27

☐ Can Fd

位置模式

position(m)

304.4

218.3

132.2

46.0

-40.1

0.0

11.8

23.6

35.4

time(s)

位置反馈

Position : +91.747 °

1.000

0.00

0.00°

位置设置

Send

Export

velocity(rad/s)

0.0024

0.0009

-0.0007

-0.0023

-0.0039

0.0

11.8

23.6

35.4

time(s)

速度反馈

Velocity : +0.000 rad/s

1.000

0.00

0.00 rpm

速度设置

Send

Export

current(A)

0.00000

-0.00012

-0.00024

-0.00037

-0.00049

0.0

11.8

23.6

35.4

time(s)

电流反馈

Current : -0.000 A

1.000

0.00

电流设置

Send

Export

Reset Data

Open

Start

Stop

电机序号

CANFD切换

CANFD下电机模式切换